Stochastic trace formula for closed, negatively curved manifolds

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Contents

1	There Is Only One n-Dimensional Wiener Measure	1
2	Piecewise Linear Approximations to Brownian Motion	1
3	The Development Map DM	1
4	The Cameron-Martin Formula	1
5	Heat Kernels as Radon-Nicodym Derivatives of Weiner Measure	1
6	Notation	1
7	Stochastic Trace Formula	2
8	Approximation and the Selberg Trace Formula My 1997 Ph.D. thesis as a blog entry.	3

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6 Notation

M is a negatively curved dim = n closed Riemannian manifold with metric g, metric connection ∇ , and (nonnegative) Laplace-Beltrami Operator Δ_M . Let $k_{-t\Delta/2}(x, y)$ represent the heat kernel on M.

Hence $k_{-t\Delta/2}(x,x) = dDM_*\mu/\sqrt{g}dx$ is the Radon-Nicodym derivative of n-dimensional Wiener Measure μ , restricted to the pull-back of continuous loop space $\Omega_t(M)|_x$, via the inverse of the Weiner measure-preserving development map DM. *Note:* $DM^{-1}\Omega_t|_x$ is not a loop space.

 Ω_t^0 is the space of continuous contractible loops on M.

 $\Omega_t[\gamma]$ is the space of continuous loops on M homotopic to the closed geodesic γ . Let γ_0 be its primitive loop.

 $DM^{-1}\Omega_t^0[\gamma]$ is the preimage of continuous contractible loops on M written as offsets homotopic to $\gamma(s) = DM(\frac{s\ell(\gamma)}{t}\vec{e}^1), 0 \le s \le t$. Think Horocyclic Coordinates – each fiber as the geometric limit of periodic geodesic spheres $S_{\gamma_0(s)}^{n-1}(k\ell(\gamma_0)), 0 \le s \le t, k \to \infty$, vectorized in the Normal Bundle over γ_0 . Our curvature constraints imply Horocyclic Coordinates for every γ_0 exist as a smooth, DM-compatible coordinate map for $\Omega_t^0[\gamma]$.

Now $\vec{x}(\tau) + \ell(\gamma)\vec{e}^1$ is the undeveloped endpoint of the "offset" kinked geodesic homotopic to $\gamma : DM(\vec{x}(\tau) + \frac{s\ell(\gamma)}{t}\vec{e}^1), 0 \leq s \leq t$. The curve is periodic with period $\ell(\gamma_0)$, and it revisits its kinked starting point $DM(\vec{x}(\tau))$ at time t, making the computation of its forward derivative $J = \lim_{s\uparrow t} DM'|_{DM(\vec{x}(\tau) + \frac{\ell(\gamma)s}{t}\vec{e}^1)}$ tractible as a linear automorphism of $T_{DM(\vec{x}(\tau))}M$. Importantly, $J_{DM(\vec{x}(\tau) + \ell(\gamma)\vec{e}^1)}$ may be constructed using **Jacobi Fields**, since DM is the (iterated) exponential map along any series of connected straight lines in \mathbb{R}^n . We will study $1/2 \int_0^t \langle dX | dX \rangle_s$, with the solution

$$X_t = X_0 + \int_0^t \sqrt{J}_{X_t} dB_t \tag{1}$$

 $Z_{-\Delta/2}(t) := \int_M k_{-t\Delta/2}(x,x) \sqrt{g} dx = \sum_{j=0}^\infty e^{-\lambda_i t/2}$ is the trace of the heat kernel. Finally let us define the following from their Radon-Nicodym derivatives:

$$DM_*\mu(\Omega_t) := \int_M DM_*\mu(\Omega_t|_x\sqrt{g}dx)$$

$$DM_*\mu(\Omega_t^0) := \int_M DM_*\mu(\Omega_t^0|_x\sqrt{g}dx)$$

$$DM_*\mu(\Omega_t[\gamma]) := \int_M DM_*\mu(\Omega_t[\gamma]|_x\sqrt{g}dx)$$
(2)

7 Stochastic Trace Formula

$$\begin{split} Z_{-\Delta/2}(t) &= DM_*\mu(\Omega_t) = DM_*\mu(\Omega_t^0) + \sum_{\{\gamma\}} DM_*\mu(\Omega_t[\gamma]) \\ DM_*\mu(\Omega_t^0) \approx_{t\to 0} (2\pi t)^{-n/2} (vol(M) + t/6 \int_M K(x)\sqrt{g}dx + O(t^2)) \text{by McKean-Singer} \\ DM_*\mu(\Omega_t[\gamma]) &= e^{-\ell(\gamma)^2/2t} \int_M DM_*\mu(e_t^{\langle J_BB_t|B_t\rangle}\Omega_t^0[\gamma]]_x\sqrt{g}dx) \text{ by Cameron-Martin} \\ &= e^{-\ell(\gamma)^2/2t} \int_{T_{\gamma_0}M} E(e_t^{J_B}|\Omega_t^0[\gamma]]_{x(\tau)}) dx^1(\tau) \dots dx^n(\tau) d\tau \\ \frac{dDM_*\mu(e^{-\ell(\gamma)x^1(t)}\Omega_t^0[\gamma])}{dx^1(\tau) \dots dx^n(\tau)d\tau}|_{y(\tau)} \approx_{t\to 0} \frac{e^{-\langle |I-J_{DM}(\bar{x}(\tau),\bar{y}(\tau)|\bar{x}(\tau)|\bar{x}(\tau)|\bar{x}(\tau)\rangle/2t}}{(2\pi t)^{(n+1)/2}} (1+O(t^2)) \text{ semi-classical limit} \\ \text{Horocyclic coordinates} : z(\tau) - x(\tau) = x + \ell(\gamma) \bar{e}^1 \Longrightarrow \\ \int_{M/S^1 \oplus S^1} k_t(x,z) dx = \lim_{j\to\infty} \frac{e^{-\ell(\gamma)^2/2t}}{\sqrt{2\pi t}} E(e^{\langle J_X_t^j \bar{x}^j|\bar{x}\rangle}) \\ &= \lim_{j\to\infty} \frac{e^{-\ell(\gamma)^2/2t}}{\sqrt{2\pi t}} \int_{M^j/S^1 \oplus S^1} \frac{1}{\sqrt{2\pi t}^{jn} \det |I-J_{X^j}|} e^{-\ell(X^j)^2/2t} X^j \end{split}$$

8 Approximation and the Selberg Trace Formula

In the dim = 2 constant curvature $-\kappa^2$ surface case,

$$\begin{split} \sqrt{J_{\vec{x},\vec{y}}}dRB &= \begin{pmatrix} e^{\kappa d(\vec{x},\vec{y})/2} & 0\\ 0 & e^{-\kappa d(\vec{x},\vec{y})/2} \end{pmatrix} \implies \\ \left\langle \sqrt{J}dRB \middle| \sqrt{J}dRB \right\rangle &= e^{\kappa \ell(B)}dRB_1^2 - e^{-\kappa \ell(B)}dRB_2^2 \\ \int_0^t \left\langle \sqrt{J}dB \middle| \sqrt{J}dB \right\rangle &= e^{\kappa \ell(\gamma)} - e^{-\kappa \ell(\gamma)} \\ \det I - J_\gamma &= (e^{\kappa \ell(\gamma)/2} - e^{-\kappa \ell(\gamma)/2})^2 \end{split}$$
(4)

which is constant over (\vec{x}, τ) , so the approximation $\approx_{t \to 0}$ line in Equation (2) becomes *exact*:

$$DM_*\mu(\Omega_t[\gamma]) = \frac{e^{-\ell(\gamma)^2/2t}\ell(\gamma_0)}{\sqrt{2\pi t}(e^{\kappa\ell(\gamma)/2} - e^{-\kappa\ell(\gamma)/2})}$$

$$\gamma(t) = \gamma_0(kt) \implies (5)$$

$$= \frac{e^{-k^2\ell(\gamma_0)^2/2t}\ell(\gamma_0)}{2\sqrt{2\pi t}\sinh k\kappa\ell(\gamma_0)/2}$$

In the dim = 3 hyperbolic manifold case, we use complex coordinates (z,\bar{z}) on the normal bundle to write

$$J_{DM(\vec{x}+(\tau+\ell(\gamma))\vec{e}^{1})} = \begin{pmatrix} e^{\kappa\ell(\gamma)} & 0 & 0\\ 0 & e^{-\kappa\ell(\gamma)+i\theta(\gamma)} & 0\\ 0 & 0 & e^{-\kappa\ell(\gamma)-i\theta(\gamma)} \end{pmatrix}$$

$$\Longrightarrow$$

$$\det I - \bot_{\gamma_{0}}^{k} = |1 - e^{-k(\kappa\ell(\gamma_{0}) - i\theta(\gamma_{0}))}|^{2}$$
(6)

and since $z = x^2 + ix^3 \implies d\bar{z} \wedge dz = (dx^2 - idx^3) \wedge (dx^2 + idx^3) = 2idx^2 \wedge dx^3$, the approximation in Equation (2) again becomes exact:

$$\kappa = 1 \implies DM_*\mu(\Omega_t[\gamma]) = \frac{e^{-k^2\ell(\gamma_0)^2/2t}\ell(\gamma_0)}{2\sqrt{2\pi t(1 - e^{-k\ell(\gamma_0)})}|e^{k\ell(\gamma_0)/2} - e^{-k(\ell(\gamma_0)/2 - i\theta(\gamma_0))}|}$$

$$\tag{7}$$

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